

Project Title: GNSS and Ionospheric Data Products for Disaster Prevention and Aviation in Magnetic Low-Latitude Regions (Phase II)

Background :

The ionosphere in the magnetic low-latitude and the magnetic equator region is observed to be highly unstable due to unique disturbance events, resulting in degradation in performances of communication and navigation. Therefore, It needs to be analyzed or forecasted based on the collected data including GNSS and other related data from the station networks in the region. Based on the measurements, data products and prediction models are implemented for positioning, navigation, communications, and aviation, especially in this region.

Targets:

1. To expand GNSS and ionospheric monitoring system into Cambodia.
2. To upgrade data products and disturbance prediction models for disaster prevention and aviation developed in Phase I
3. To develop a low-cost real-time kinematics (RTK) receiver system and test its performance during Plasma Bubble using the data collected from newly installed stations in Phase I.
4. To continue the recently established GNSS and SW Excellence Center at KMITL and conduct capacity building for domestic network and partnered institutions on GNSS technology, ionosphere, and Space Weather parameters understanding.

Speaker: Asst. Prof. Dr. Lin Min Min Myint, KMITL, Thailand



Project Title: GNSS and Ionospheric Data Products for Disaster Prevention and Aviation in Magnetic Low- Latitude Regions (Phase II)

Project Members : 6 Institutes from 4 countries

Party	Name	Party	Name
NICT, Japan	TSUGAWA Takuya	CMU, Thailand	Tharadol Komolmis
	HOZUMI Kornyanat		Prayoonsak Praychan
KMITL, Thailand	Pornchai Supnithi	NUOL, Lao	Donekeo Lakanchan
	Watid Phakphisut		Phutsavanh Thogphanh
	Punyawi Jamjareegulgarn		Phouthong Southisombath
	Prasert Kenpankho	CADT, Cambodia	Khema Van
GISTDA, Thailand	Sittiporn Channums		Thayheng Nhem

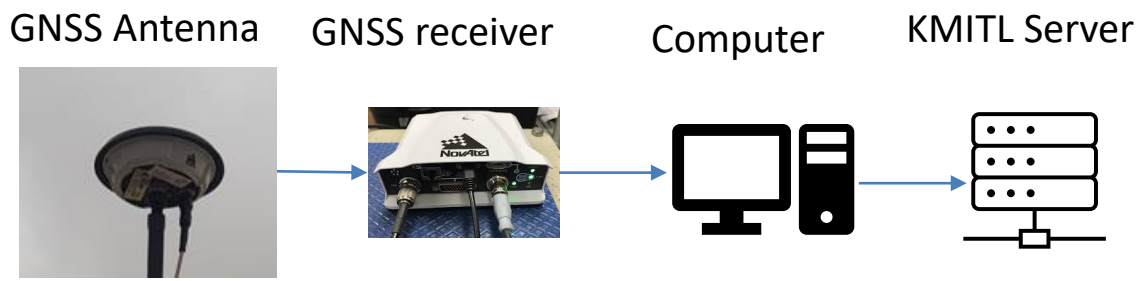
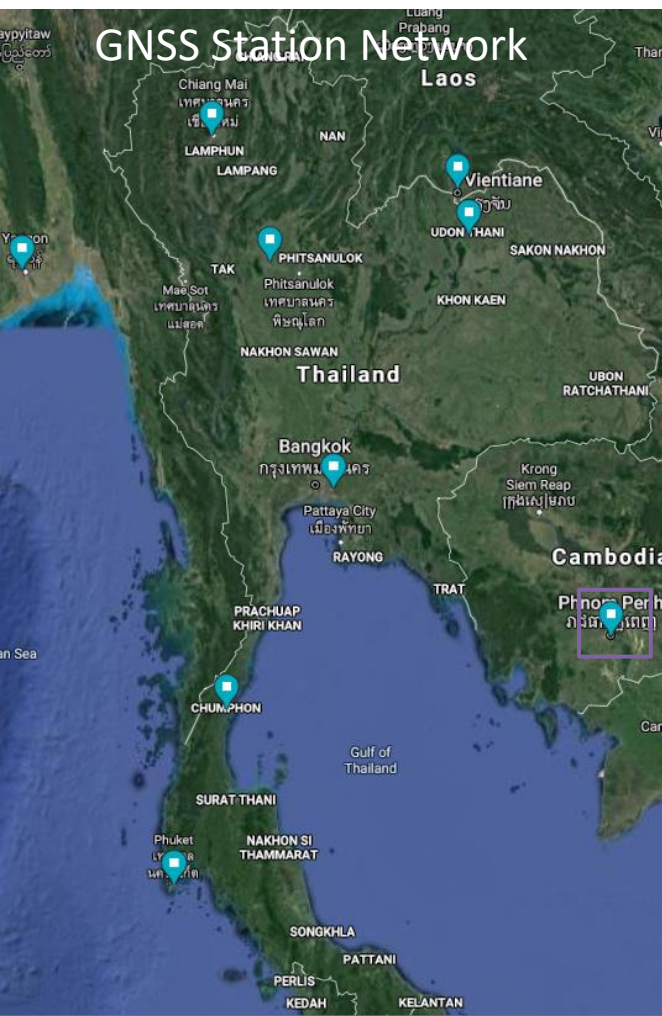
6 Associate Project Members.

Project Duration : April 1st, 2021 - March 31st, 2023 (24 Months)

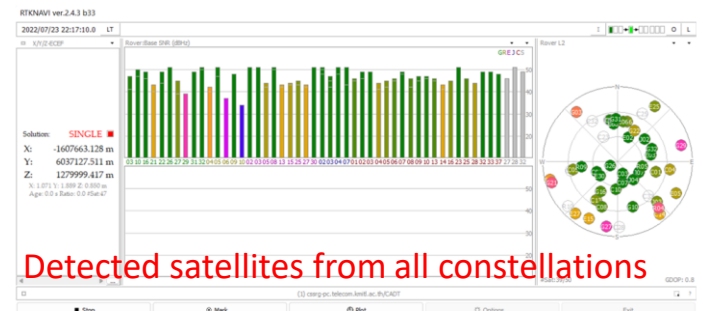
Project Budget: First year (April 1st, 2021 – March 31st, 2022) : 39,880 USD
 Second year (April 1st, 2022 – March 31st, 2023) : 39,980 USD

R&D description		Subcategories		Responsible members
A :	To Install dual-frequency GNSS receiver in Cambodia			KMITL, CADT, NICT
B:	To upgrade daily GNSS and SW data products for disaster and aviation	a:	Modify daily GNSS data such as 2-D TEC maps, ROTI data products including the data from Laos, Cambodia	KMITL, CADT, NUOL
		b:	Upgrade daily ionospheric data products for Communications and Aviation.	KMITL, NICT, CADT, GISTDA, CMU
		c:	Develop AI and Machine learning model the applications of GNSS and Aviation	KMITL, NICT
C	To develop and test a real-time kinematics (RTK) positioning system using the post- processed data from newly installed GNSS network.			KMITL, NUOL, CADT
D	To support capacity- building for domestic network and partnered institutions on GNSS technology, ionosphere, basic space weather			ALL

Project Activities: A: Expanding GNSS and Ionospheric Monitoring System into Cambodia



Checking satellites availability and received signal SNR



CADT Innovation Center Building



NovAtel PwrPak7 GNSS receiver, GNSS-850 GNSS antenna, computer and other required equipment have been installed at Cambodia Academy of Digital Technology (CADT), Phnom Penh, Cambodia by the project members from KMITL, Thailand and CAD, Cambodia together.

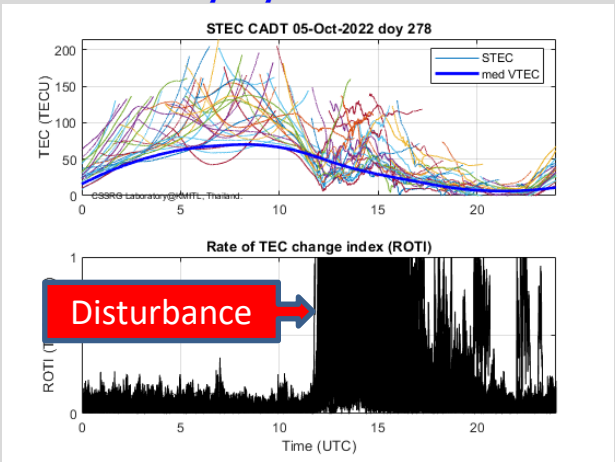
Budget: \$20,221.70 GNSS Receiver Set (in 2021) + \$800.00 Installation Trip Expense

Project Activities:

A: Expanding GNSS and Ionospheric Monitoring System into Cambodia

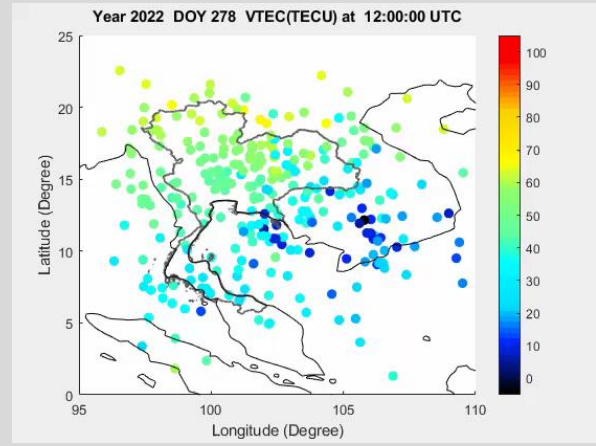
We have studied Ionospheric Variation and Disturbance Information based on GNSS data from the new CADT station, Cambodia together with other stations.

Date: 5/10/2022

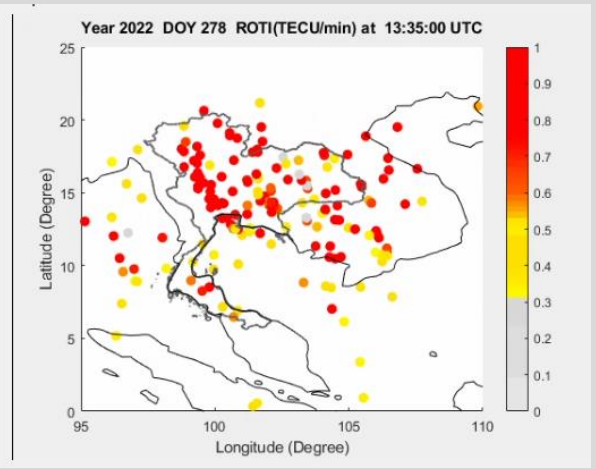
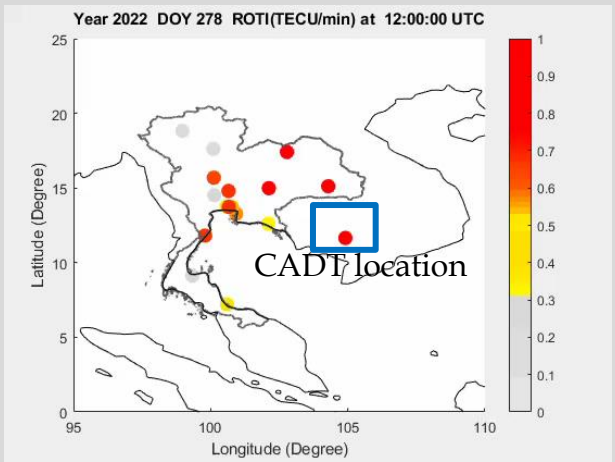


The Rate of TEC index (ROTI) at each stations

TEC at Ionospheric Pierce Point (IPP)

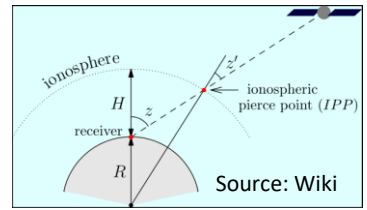


ROTI at Ionospheric Pierce Point (IPP)



Using the data from CADT, we can observe more coverage area of the ionospheric variations.

Note: *ionospheric pierce point (IPP)* is the signal transmitted from the satellite to the receiver crosses the ionospheric shell in IPP.

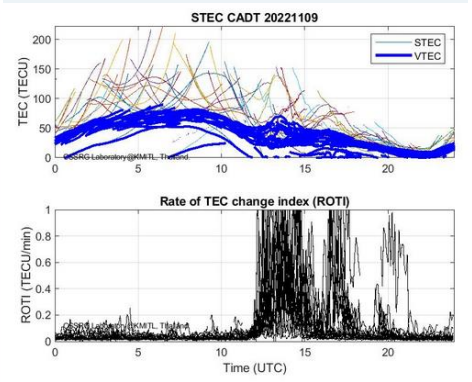


Source: Wiki

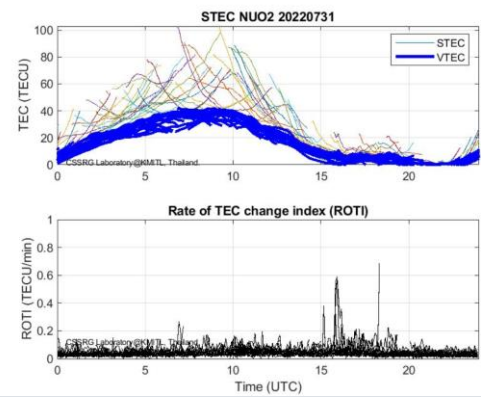
a) Modify daily GNSS data such as 2-D TEC maps, ROTI data products including the data from Laos, Cambodia

Daily Slant TEC (STEC) and ROTI Plots

Cambodia (CADT)

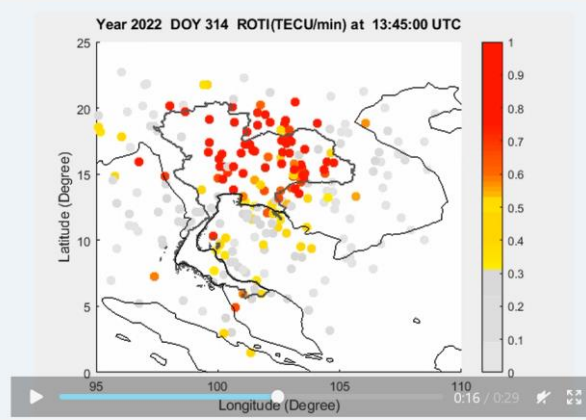
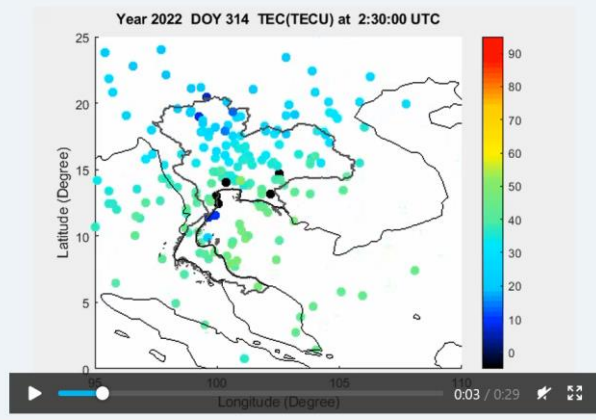


Laos (NUOL)



Using the data from newly installed stations, we can extend the coverage area of the ionospheric observation and increase the resolution of the TEC and ROTI maps.

TEC and ROTI Maps with Data from new CADT and NUOL stations



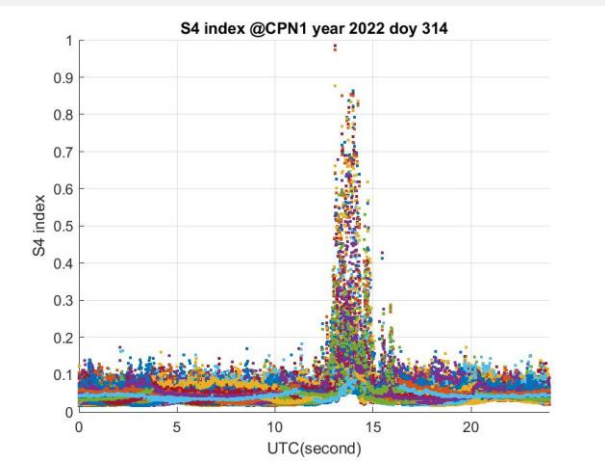
Daily Maps and Plots can be observed at KMITL's GNSS and SW Excellence Center
http://iono-gnss.kmitl.ac.th/?page_id=807

b) Upgrade daily ionospheric data products for Communications and Aviation.

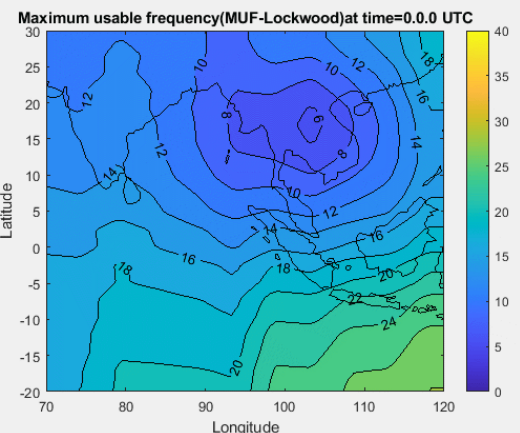
S4 index is used to measure the severity of scintillation (fluctuation) on GNSS or GPS signals.

Daily S4 at Chumphon Station near magnetic equator can be observed at KMITL's GNSS and SW Excellence Center http://iono-gnss.kmitl.ac.th/?page_id=807

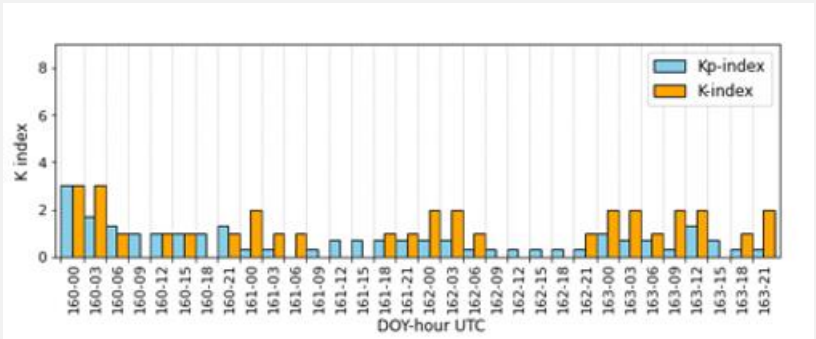
Daily S4 Index from Chumphon Station



Maximum usable frequency (MUF) Map

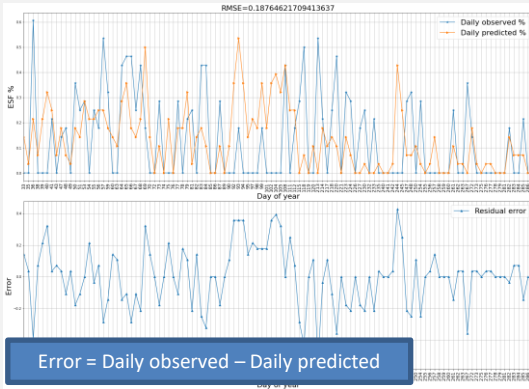
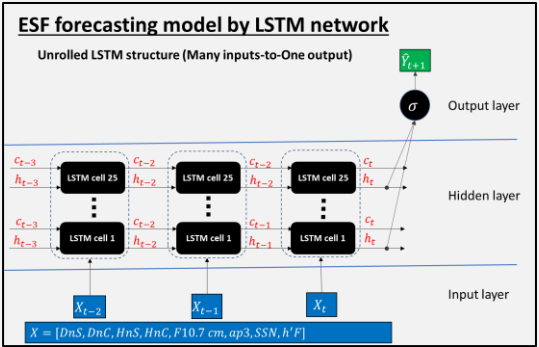


Local Geomagnetic K index from Magnetic Equator Phuket Station



c) Develop AI and Machine learning model for the applications of GNSS and Aviation.

Develop the Equatorial Spread-F (ESF) forecasting model using Long-Short Term Memory (LSTM)



Prediction of the ESF daily percentage in 2019

- ESF daily percentage prediction can achieve 0.18 of RMSE
- High errors are seen around DOY 92 – DOY 213

Develop a machine learning model using support vector machines (SVM) and Singular Value Decomposition (SVD) to detect the occurrences of equatorial plasma bubbles



Compare 4 Kernels	Accuracy of SVM model (%)	Accuracy of SVD+SVM model (%)
Linear	82.58%	83.05%
Sigmoid	62.77%	63.42%
Radial Basis Function	86.67%	87.58%
Polynomial Kernel	83.76%	84.47%

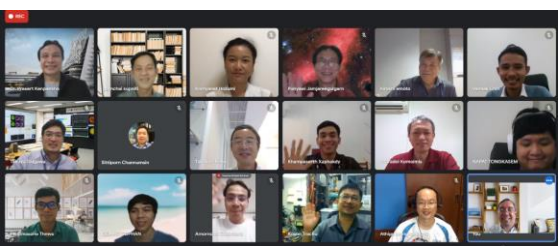
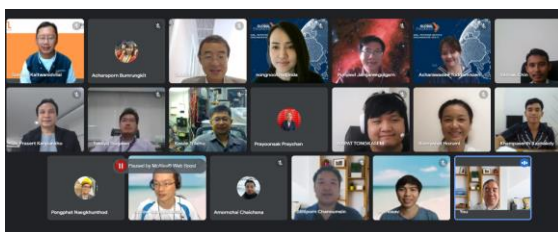
An SVM model using RBF Kernels provides the highest accuracy.

Project Activities: D: Capacity Building and Knowledge Sharing

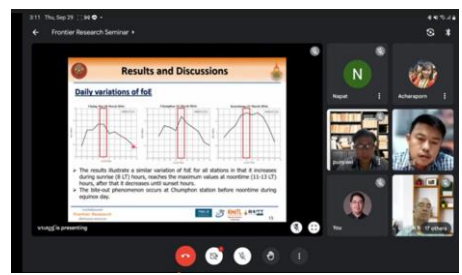
No.	Activity	Mode/Location	Date	# Participant
1	Project Kick-Off Meeting and Technical Workshop	Online	July 29 th , 2021	35
2	GNSS & S/W Training Workshop	Onsite, at CADT in Cambodia	July 21 st , 2022	20
3	PMU-B Frontier Research & ASEAN-IVO Seminar	Hybrid, at KMITL in Thailand	Sept. 29 th , 2022	40

Project Kick-Off Meeting and Technical Workshop

PMU-B Frontier Research & ASEAN-IVO Seminar



GNSS & S/W Training Workshop at CADT



Scientific Contribution:

Published Journal Papers:

No:	Paper title:	Author names	Affiliation	Journal name:	The publisher of the Journal	The volume number and Pages
1	Analysis of local geomagnetic index under the influence of equatorial electrojet (EEJ) at the equatorial Phuket geomagnetic station in Thailand	L.M. M. Myint, K. Hozumi S. Saito P. Supnithi	KMITL, Bangkok, Thailand NICT, Tokyo, Japan ENRI, NIMPAT, Tokyo, Japan	Advances in Space Research	Committee on Space Research (COSPAR)	Vol. 70, No. 5, 1 September 2022, pp 1429-1440

Presentations at International Conferences:

No:	Paper title:	Author names	Affiliation	Conference name:	The date of the conference	The venue of the conference
1	Equatorial Plasma Bubble detection by Support Vector Machine at Chumphon Station, Thailand	T.Thanakulketsarat, P. Supnithi, L. Myint, K. Hozumi	KMITL, Bangkok, Thailand NICT, Tokyo, Japan	2022 37th ITC CSCC	05-08/07/2022	Duangjitt Hotel, PHUKET, THAILAND
2	Comparison study of amplitude scintillation between GNSS and satellite beacon receivers in Thailand	K. Seechai L. Myint, K. Hozumi P. Supnithi,	KMITL, Bangkok, Thailand NICT, Tokyo, Japan	2022 37th (TC CSCC	05-08/07/2022	Duangjitt Hotel, PHUKET, THAILAND
3	Support Vector Machine (SVM) for equatorial plasma bubble detection from VHF Radar Images at Chumphon VHF Radar Station, Thailand	T.Thanakulketsarat, P. Supnithi, L. Myint, K. Hozumi	KMITL, Bangkok, Thailand NICT, Tokyo, Japan	ISEA-16	12-16/09/2022	Uji Campus, Kyoto University, Kyoto, Japan
4	Time Series Prediction of the Equatorial Spread-F Occurrence using the LSTM network	P. Thammavongsy, P. Supnithi, L. Myint, K. Hozumi	KMITL, Bangkok, Thailand NICT, Tokyo, Japan	ISEA-16	12-16/09/2022	Uji Campus, Kyoto University, Kyoto, Japan
5	Study of Equatorial Geomagnetic Field Activities and its Relationship with Ionospheric disturbances at Low-Latitude	L. Myint, K. Seechai K. Hozumi P. Supnithi,	KMITL, Bangkok, Thailand NICT, Tokyo, Japan	ISEA-16	12-16/09/2022	Uji Campus, Kyoto University, Kyoto, Japan

Data product using ionospheric parameters and other relative data collected from GNSS receiver, Ionosonde, VHF radar, and magnetometer can

- Enhance **understanding of ionospheric disturbance in magnetic equator and low-latitude region**, particularly, ASEAN region.
- Be useful in detecting ionospheric disturbances and geomagnetic storms for **aviation and HF communications**, prevalent, in aviation and communications in a disaster situation.

Better disturbance characterization is required to determine performance of **high-accuracy GNSS systems** used in other industries such as **smart agriculture and autonomous driving**.

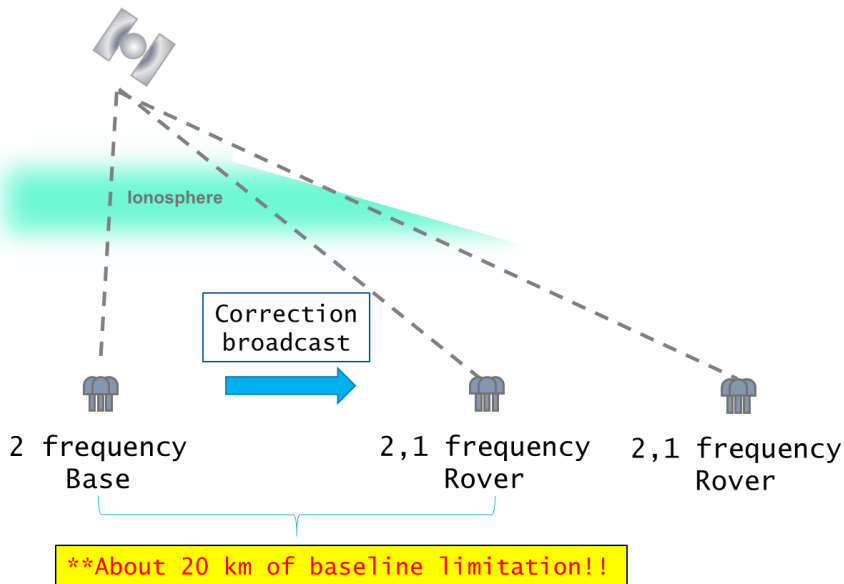
Regional data collection is important for long-term study and is useful to **global model improvement** (such as IRI model and IGS model).

The researchers from the partnered institutes in Cambodia and Laos are encouraged to work on **joint research** with the data collected for local communities.

Conclusion:

- ❑ The project has accomplished installing the GNSS receiver system in CADT, Phnom Penh, Cambodia.
- ❑ The GNSS data from the new station is available and they are being analyzed to observe the ionospheric disturbances.
- ❑ The data products for ionosphere observation such as TEC and ROTI 2-D plots and maps have been modified to include the new stations from Laos and Cambodia.
- ❑ We maintained and upgraded daily ionospheric data products such as S4 index plots, MUF maps, and K-index for Communications and Aviation. We also developed AI and machine learning models to analyze and predict ESF and EPB using the measured data from Ionosonde and the newly installed VHF radar in Chumphon, Thailand.
- ❑ We have organized three workshops and seminars for capacity building and knowledge sharing.

To develop and test a real-time kinematics (RTK) positioning system using the post-processed data from a newly installed GNSS station in Laos and Cambodia.



Methods

- ✓ Implement a low-cost RTK receiver system.
- ✓ Test the developed system and commercial RTK system using the collected data from our station networks, particularly, those newly installed in Phase I.

To establish Space Weather and GNSS technologies Learning Centers in National University of Laos in Laos and KMITL Chumphon Campus, Thailand.